

A Classification of Totally Umbilical Semi-invariant Submanifolds of Riemannian Product Manifolds

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Abstract

This paper is dedicated to the study of totally umbilical semi-invariant submanifolds in the setting of Riemannian product manifolds. Moreover, by using curvature tensor, we obtain a classification for these submanifolds.

1 Introduction

In 1978, Bejancu introduced the notion of CR-submanifolds of a Kaehler manifold [1] which generalizes the holomorphic and totally real submanifolds. In fact, this provided a single setting to study the holomorphic and totally real submanifolds. Later, Chen [3] studied CR-submanifolds in the setting of Kaehler manifolds. The geometric point of view of CR-submanifolds was taken up by a number of differential geometers and several papers have appeared in the literature (for instance, [7], [8], [9]). However, the contact version of the CR-submanifolds was explored by Bejancu and Papaghuic [2]; more precisely, they studied contact CR-submanifolds with the name of Semi-invariant submanifolds in the frame of Sasakian manifolds. Moreov,er

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Chen [4] classified totally umbilical CR-submanifolds of the Kaehler manifolds. Furthermore, Deshmukh and Husain [9] studied totally umbilical CR-submanifolds of a Kaehler manifold. In 2003, Sahin [6] studied Semi-invariant submanifolds of Riemannian product manifolds. Later, Atceken [11] extended the study of Semi-invariant submanifolds in the setting of Riemannian product manifolds. In the present paper, our aim is to study the totally umbilical Semi-invariant submanifolds of the Riemannian manifolds. In fact, we obtain a classification for these submanifolds.

2 Preliminaries

Let (M_1, g_1) and (M_2, g_2) be the Riemannian manifolds with dimensions m_1 and m_2 respectively and let $M_1 \times M_2$ be the Riemannian product manifold of M_1 and M_2 . We denote the projection mapping of $T(M_1 \times M_2)$ onto TM_1 and TM_2 by σ_* and π_* respectively. Then we have $\sigma_* + \pi_* = I$, $\sigma_*^2 = \sigma_*$, $\pi_*^2 = \pi_*$ and $\sigma_* \circ \pi_* = \pi_* \circ \sigma_* = 0$, with \star denoting mean derivatives.

The Riemannian metric of the Riemannian product manifold $M = M_1 \times M_2$ is defined by

$$g(X, Y) = g_1(\sigma_*X, \sigma_*Y) + g_2(\pi_*X, \pi_*Y),$$

for any $X, Y \in T\bar{M}$. If we set $F = \sigma_* - \pi_*$, then $F^2 = I$, $F \neq I$ and g satisfies the condition

$$g(FX, Y) = g(X, FY),$$

for any $X, Y \in T\bar{M}$. Thus F defines an almost Riemannian product structure on \bar{M} . We denote the Levi-Civita connection on \bar{M} by $\bar{\nabla}$. Then the covariant derivative of F is defined as

$$(\bar{\nabla}_X F)Y = \bar{\nabla}_X FY - F\bar{\nabla}_X Y,$$

for any $X, Y \in TM$. We say that F is parallel with respect to the connection $\bar{\nabla}$ if we have $(\bar{\nabla}_X F)Y = 0$. From [10], we know that F is parallel; that is, F is Riemannian product structure.

Let \bar{M} be a Riemannian product manifold with Riemannian product structure F and M be an immersed submanifold of \bar{M} . We also let g be the induced metric tensor on M as well as on \bar{M} . If $\bar{\nabla}$ is the Levi-civita connection on \bar{M} , then the Gauss and Weingarten formulas are given, respectively, as

$$\bar{\nabla}_X Y = \nabla_X Y + h(X, Y) \tag{2.1}$$

$$\bar{\nabla}_X V = -A_V X + \nabla_X^\perp V, \tag{2.2}$$

for any $X, Y \in TM$ and $V \in T^\perp M$, where ∇ is the connection on M and ∇^\perp is the connection in the normal bundle, h is the second fundamental form of M and A_V the shape operator of M . The second fundamental form h and the shape operator A_V are related by

$$g(A_V X, Y) = g(h(X, Y), V). \tag{2.3}$$

For any $X \in TM$, we can write

$$FX = fX + \omega X, \tag{2.4}$$

where fX and ωX are the tangential and normal components of FX , respectively and for $V \in T^\perp M$

$$FV = tV + nV, \tag{2.5}$$

where tV and nV are the tangential and normal components of FV . The submanifold M is said to be invariant if ω is identically zero. On the other hand, M is said to be an anti-invariant submanifold if f is identically zero.

The covariant derivatives of f, ω, t and n are defined as

$$(\bar{\nabla}_X f)Y = \nabla_X fY - f\nabla_X Y \tag{2.6}$$

$$(\bar{\nabla}_X \omega)Y = \nabla_X^\perp \omega Y - \omega \nabla_X Y \tag{2.7}$$

$$(\bar{\nabla}_X t)V = \nabla_X tV - t\nabla_X V \tag{2.8}$$

$$(\bar{\nabla}_X n)V = \nabla_X^\perp nV - n\nabla_X^\perp V. \tag{2.9}$$

Using (2.1),(2.2) (2.4) and (2.6), we get

$$(\bar{\nabla}_X f)Y = A_{\omega Y} X + th(X, Y). \tag{2.10}$$

Now, we define the Semi-invariant submanifold of a Riemannian product manifold \bar{M} as follows:

Definition 2.1.[6] A Submanifold M of a Riemannian product manifold \bar{M} is said to be semi-invariant submanifold if there exist two orthogonal complimentary distributions D and D^\perp satisfying

- (i) $TM = D \oplus D^\perp$
- (ii) D is a invariant distribution; i.e., $FD \subseteq D$.

(iii) D^\perp is anti-invariant distribution; i.e., $FD^\perp \subseteq T^\perp M$.

If μ is invariant subspace under F of the normal bundle $T^\perp M$, then, in the case of semi-invariant submanifold, the normal bundle $T^\perp M$ can be decomposed as

$$T^\perp M = \mu \oplus \omega D^\perp.$$

A semi-invariant submanifold M is said to be totally umbilical if

$$h(X, Y) = g(X, Y)H, \quad (2.11)$$

where $H = \frac{1}{n}(\text{trace } h)$ is called the mean curvature vector. For the totally umbilical semi-invariant submanifold M , the equations (2.1) and (2.2) take the form

$$\bar{\nabla}_X Y = \nabla_X Y + g(X, Y)H, \quad (2.12)$$

$$\bar{\nabla}_X V = -g(H, V)X + \nabla_X^\perp V. \quad (2.13)$$

The Riemannian curvature tensor is defined as

$$R(X, Y)Z = \bar{\nabla}_X \bar{\nabla}_Y Z - \bar{\nabla}_Y \bar{\nabla}_X Z - \bar{\nabla}_{[X, Y]} Z. \quad (2.14)$$

The equation of Coddazi for totally umbilical semi-invariant submanifold M is given by

$$\bar{R}(X, Y, Z, V) = g(Y, Z)g(\nabla_X^\perp H, V) - g(X, Z)g(\nabla_Y^\perp H, V), \quad (2.15)$$

where $\bar{R}(X, Y, Z, V) = g(\bar{R}(X, Y)Z, V)$ and X, Y, Z are vector fields on M and $V \in T^\perp M$.

It is easy to see that the Riemannian curvature tensor for Riemannian product manifolds satisfies the following properties

$$(a) \bar{R}(FX, FY)Z = \bar{R}(X, Y)Z \quad (b) F\bar{R}(X, Y)Z = \bar{R}(X, Y)FZ. \quad (2.16)$$

By an extrinsic sphere we mean a submanifold of an arbitrary Riemannian manifold which is totally umbilical and has a nonzero parallel mean curvature vector [9].

3 Totally Umbilical semi-invariant submanifolds of Riemannian product manifolds

In this section, we will study a special class of semi-invariant submanifolds which are totally umbilical. Throughout the section, we consider M as a totally umbilical semi-invariant submanifold of a Riemannian product manifold. Now we have the following theorem:

Theorem 3.1. Let M be a totally umbilical semi-invariant submanifold of a Riemannian product manifold \bar{M} such that the mean curvature vector $H \in \mu$. Then one of the following statement is true

- (i) M is totally geodesic,
- (ii) M is anti-invariant.

Proof. For $N \in FD^\perp$ and $X \in D$, we have

$$\bar{\nabla}_X FN = F\bar{\nabla}_X N. \tag{3.17}$$

Using equations (2.12) and (2.13) the above equation becomes

$$\nabla_X FN = -FXg(N, H) + F\nabla_X^\perp N.$$

By the assumption that $H \in \mu$, the above equation reduces to

$$\nabla_X FN = F\nabla_X^\perp N,$$

which implies that $\nabla_X^\perp N \in FD^\perp$, for any $N \in FD^\perp$. Also, we have $g(N, H) = 0$ for any $N \in FD^\perp$. Then

$$g(\nabla_X^\perp N, H) = -g(N, \nabla_X^\perp H) = 0.$$

The above equation gives $\nabla_X^\perp H \in \mu$.

Now, for any $X \in D$, we have

$$\bar{\nabla}_X FH = F\bar{\nabla}_X H.$$

Using Gauss and Weingarten formulae and the assumption that M is a totally umbilical, the above equation takes the form

$$Xg(H, FH) + \nabla_X^\perp FH = -FXg(H, H) + F\nabla_X^\perp H,$$

or

$$\nabla_X^\perp FH = -FXg(H, H) + F\nabla_X^\perp H.$$

Comparing tangential parts

$$fXg(H, H) = 0.$$

From the above equation, it is evident that $fX = 0$ or $H = 0$; i.e., M is either totally geodesic or anti-invariant.

Now, for any $Z \in D^\perp$, using equation (2.10)

$$-f\nabla_Z Z = A_{\omega Z}Z + th(Z, Z).$$

Taking the inner product with $W \in D^\perp$, the above equation takes the form

$$-g(f\nabla_Z Z, W) = g(A_{\omega Z}Z, W) + g(th(Z, Z), W).$$

As M is a totally umbilical semi-invariant submanifold, the above equation becomes

$$g(Z, W)g(H, FZ) + g(tH, W)\|Z\|^2 = 0, \quad (3.18)$$

which has a solution if either $H \in \mu$ or $\dim D^\perp = 1$.

If, in addition, $H \notin \mu$, then we have

Theorem 3.2. Let M be a totally umbilical semi-invariant submanifold of a Riemannian product manifold \bar{M} such that the dimension of invariant distribution ≥ 4 . Then M is an extrinsic sphere.

Proof. Since $\dim D \geq 4$, we can choose a set of orthogonal vectors $X, Y \in D$ such that $g(X, Y) = 0$ and $g(X, FY) = 0$. Now, from equation (2.16)(b), we have

$$F\bar{R}(X, Y)Z = \bar{R}(X, Y)FZ.$$

Replacing Z by FY

$$F\bar{R}(X, Y)FY = \bar{R}(X, Y)F^2Y.$$

$$F\bar{R}(X, Y)FY = \bar{R}(X, Y)Y.$$

Taking the inner product with $V \in T^\perp M$, we get

$$g(F\bar{R}(X, Y)FY, V) = g(\bar{R}(X, Y)Y, V),$$

or

$$\bar{R}(X, Y, FY, nV) = \bar{R}(X, Y, Y, V).$$

Now, from Coddazi equation

$$g(Y, FY)g(\nabla_X^\perp H, V) - g(X, FY)g(\nabla_Y^\perp H, V) = g(Y, Y)g(\nabla_X^\perp H, V) - g(X, Y)g(\nabla_Y^\perp H, V),$$

or

$$\|Y\|^2 g(\nabla_X^\perp H, V).$$

From the above equation it is evident that $g(\nabla_X^\perp H, V) = 0$; i.e., $\nabla_X^\perp H = 0 \forall X \in D$. If we take $X \in D^\perp$ and $Y \in D$, then, by similar calculation, we obtain $\nabla_X^\perp H = 0, \forall X \in D^\perp$. Hence, the submanifold is an extrinsic sphere.

Theorem 3.3. Let M be a totally umbilical semi-invariant submanifold of a Riemannian product manifold \bar{M} . Then M is either

- (i) totally geodesic,
- (ii) anti-invariant,
- (iii) $\dim D^\perp = 1$,
or
- (iv) an Extrinsic sphere.

(Case (iv) holds if $\dim M \geq 5$.)

Proof. If $H \in \mu$, then, by Theorem 3.1, M is either totally geodesic or anti-invariant which is case (i) or case (ii). If $H \notin \mu$, then equation (3.18) has a solution if $\dim D^\perp = 1$ which is case (iii). Moreover, if $H \notin \mu$ and the dimension D of the invariant distribution is at least 4, then, by Theorem 3.2, M is an extrinsic sphere. The proof of the theorem is now complete.

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